



ExcelsiusGPS™

The Next Revolution in Robotic Spine Surgery

ExcelsiusGPS™ is a revolutionary robotic navigation system. The system is designed by surgeons to be intuitive and streamline the surgical workflow. Real-time tracking of instruments and implants, along with audible, visual, and tactile feedback, enables confidence in the system throughout the procedure.

ROBOTIC GUIDANCE

The **active End Effector** regularly communicates with the camera and system to dynamically adjust the robotic arm position to optimize kinematics. The End Effector aligns the guide tube along the trajectory to enable direct implant placement with GPS instruments.



NAVIGATION

The system provides **real-time feedback** on instrument positioning with respect to patient anatomy which may significantly reduce the amount of radiation required throughout the procedure. The navigation capability closes the loop for the robotic guidance, confirm final implant positioning, and ultimately provide more information for surgeons to make informed decisions.



MINIMAL SET-UP

Setup for ExcelsiusGPS™ only involves system draping and simple positioning of the frameless robotic arm. When the procedure is complete, the camera stand docks into the base station as one mobile unit, for **easy storage and movement** between operating rooms.





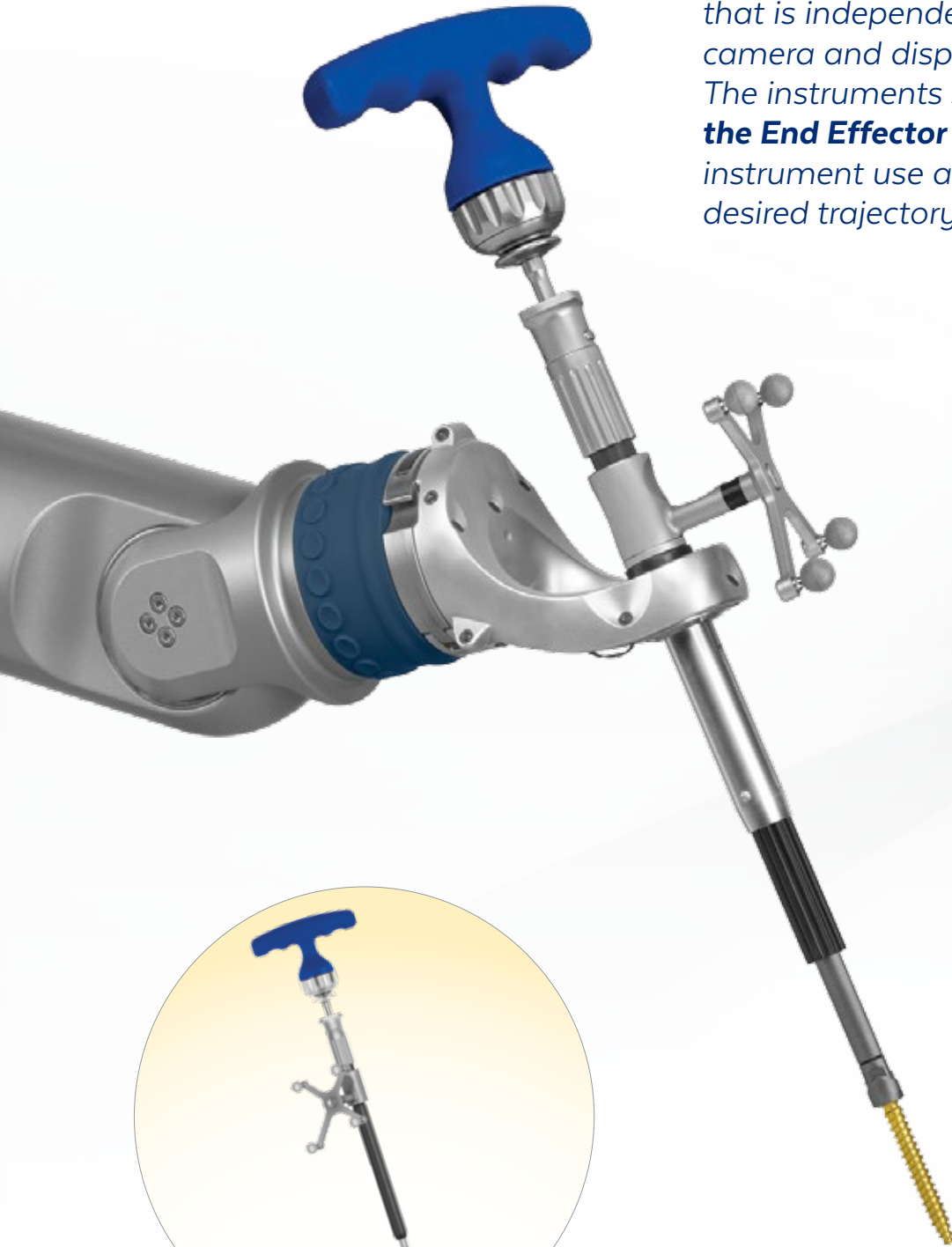
RIGID ROBOTIC ARM

The rigid robotic arm automatically moves the End Effector to the selected trajectory. The rigidity of the robotic arm enables the End Effector to **remain stable during implant insertion on steep trajectories.**



FULLY INTEGRATED INSTRUMENTS

GPS instruments each have an array that is independently recognized by the camera and displayed on the monitor. The instruments **seamlessly engage with the End Effector** to enable one-handed instrument use and confirm alignment on desired trajectory.





IMAGING COMPATIBILITY

*ExcelsiusGPS™ is **compatible with preoperative CT, intraoperative CT, and fluoroscopy imaging systems.** This versatility allows the system to fit into any surgical workflow and enables planning and navigation in 2D or 3D.*

Capital Components	
Part No.	Description
6143.1002	System, ExcelsiusGPS™, 240V
6143.2101	Tablet PC, ExcelsiusGPS™
6143.2102	Fixture, Fluoro Navigation, 9 in

Software Modules	
Part No.	Description
6143.5001	Spine Software Module
6143.5002	Fluoroscopy Software Module

Instruments	
Part No.	Description
9143.9001	15mm End Effector, GPS
9143.9002	Navigation, GPS
9143.9003	REVERE®, GPS
9143.9004	CREO® and CREO AMP®, GPS
9143.9005	CREO MIS®, GPS
9143.9006	REVOLVE®, GPS
9143.9007	CREO MCS®, GPS
9143.9008	SI-LOK®, GPS
9143.9009	ELLIPSE® and QUARTEX™, GPS
9143.9010	17mm End Effector, GPS

Disposables	
Part No.	Description
6143.2001S	Arm Drape, 10 ct
6143.2003S	Monitor Drape, 20 ct
8801002	Passive Markers, 60 ct
8800966	Passive Markers, 30 ct

OUTSIDE THE U.S. ONLY

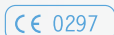


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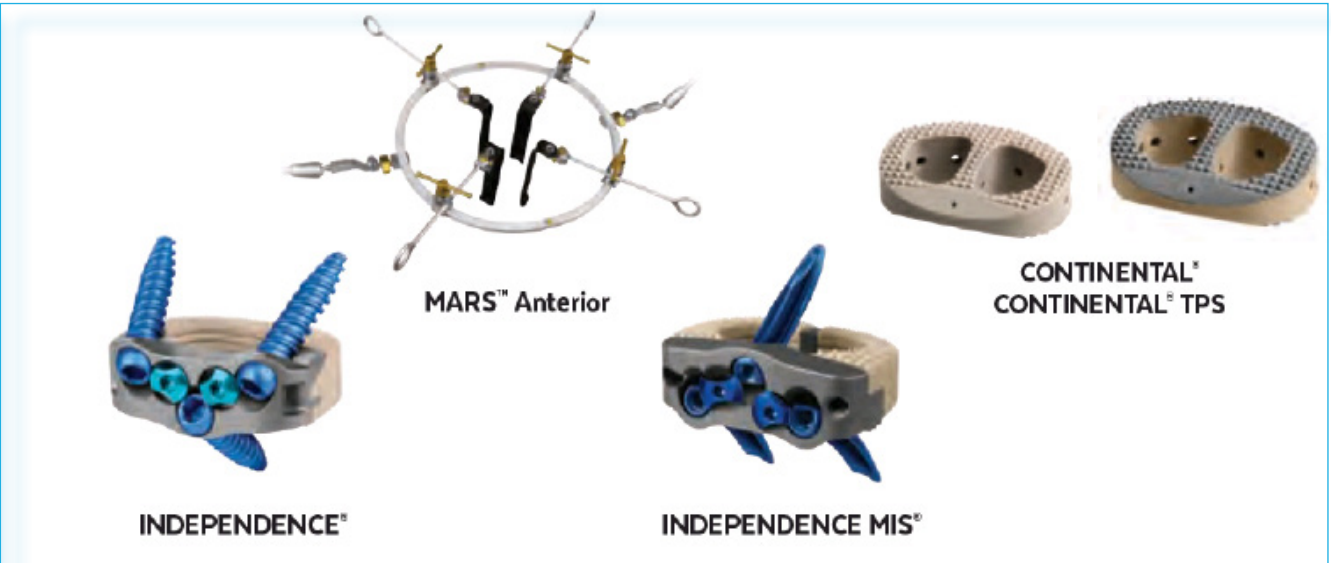
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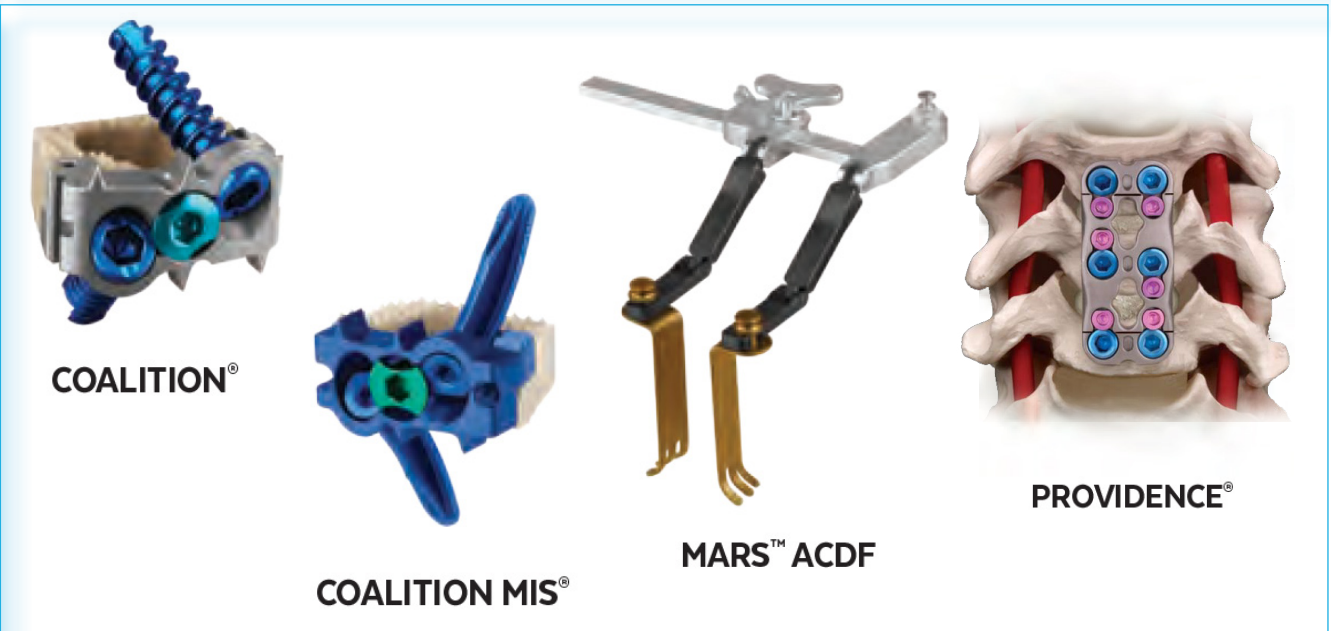
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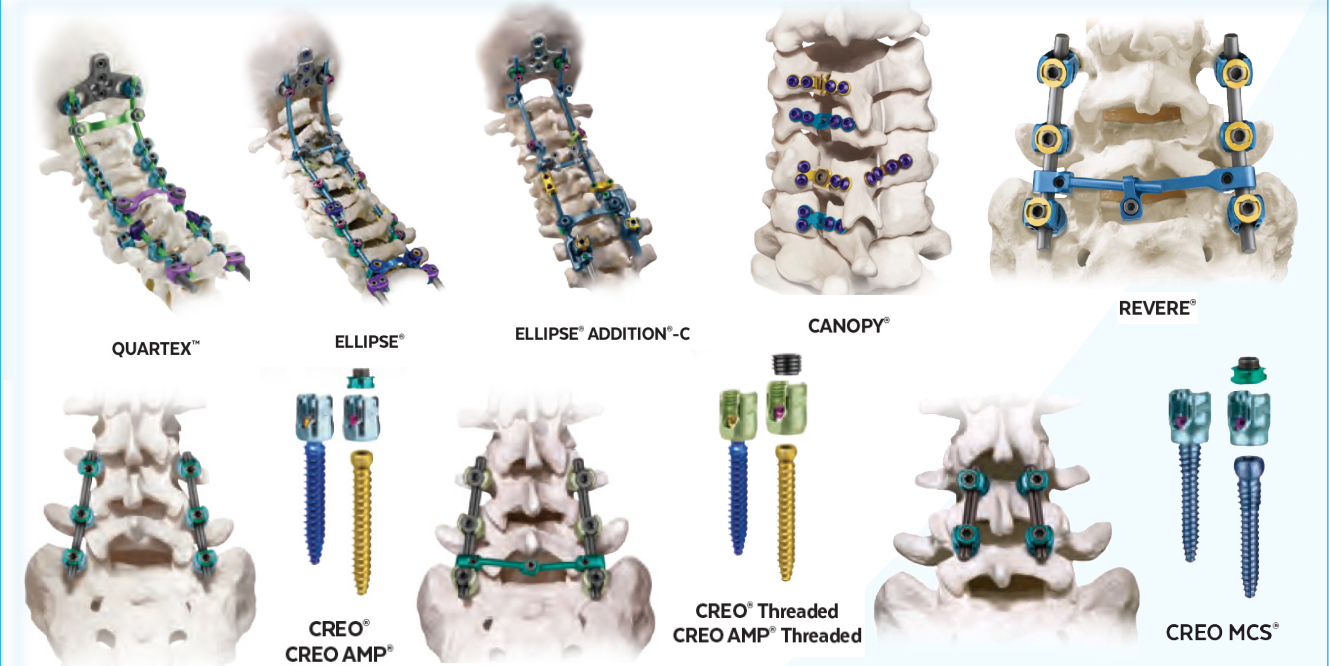
FIJACION CERVICAL ANTERIOR



CORPECTOMIA



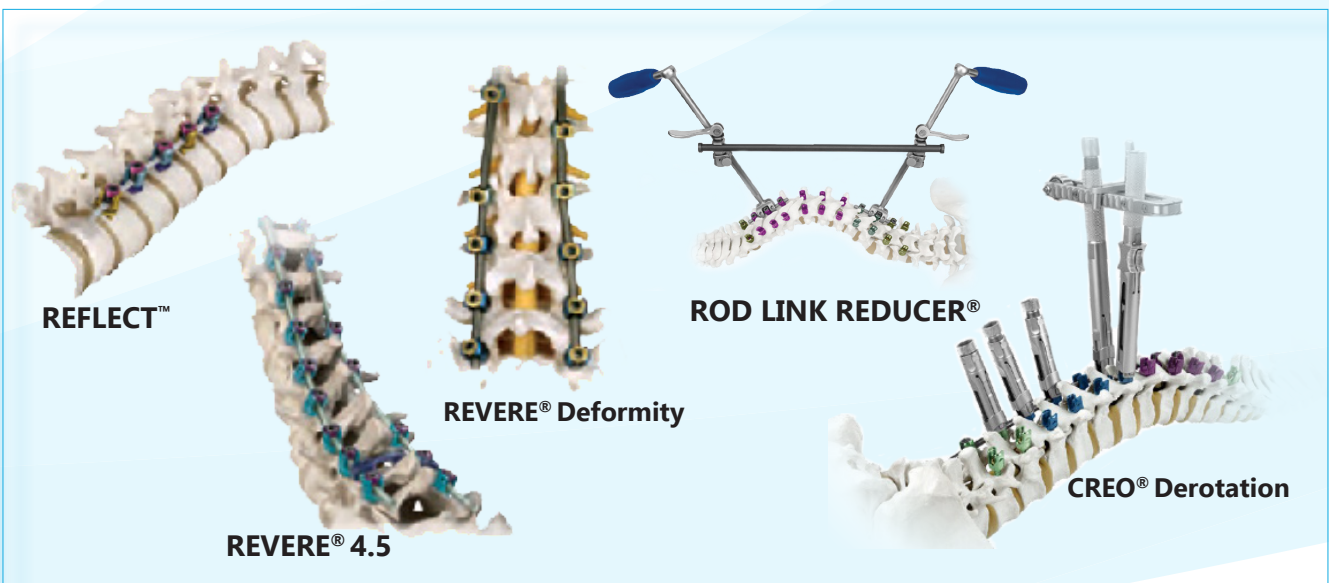
FIJACION VERTEBRAL



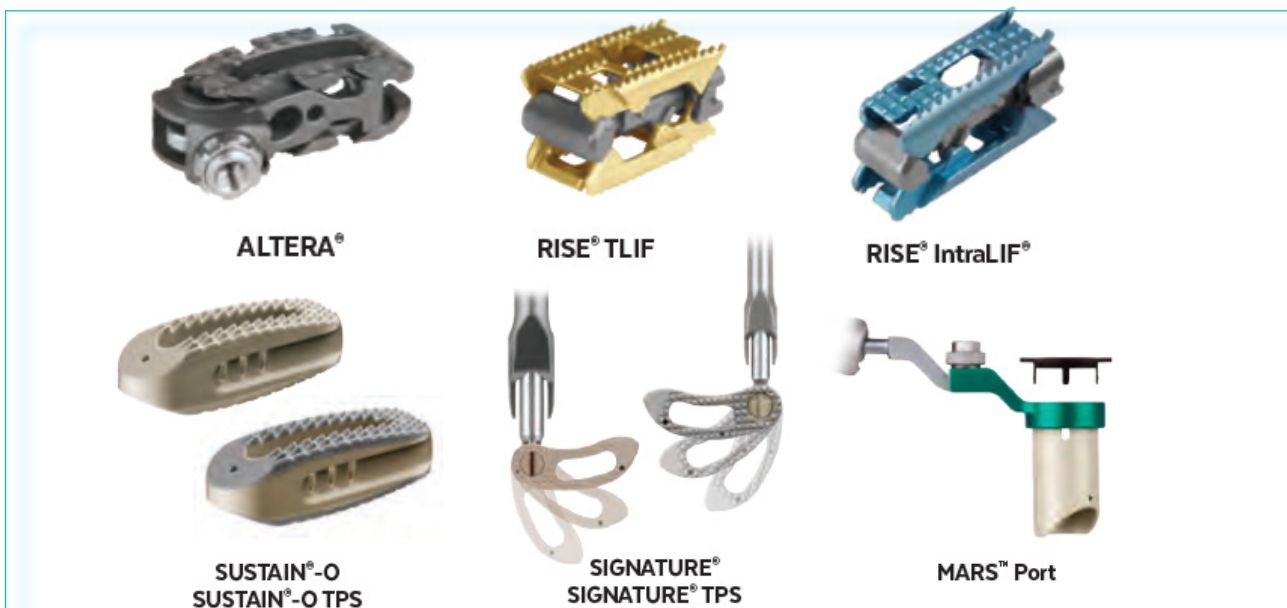
ESTABILIZACION DINAMICA



DEFORMIDAD



CAJAS INTERSOMATICAS LUMBARES



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MIS

